



Fingerprinting hardware devices using clock-skewing

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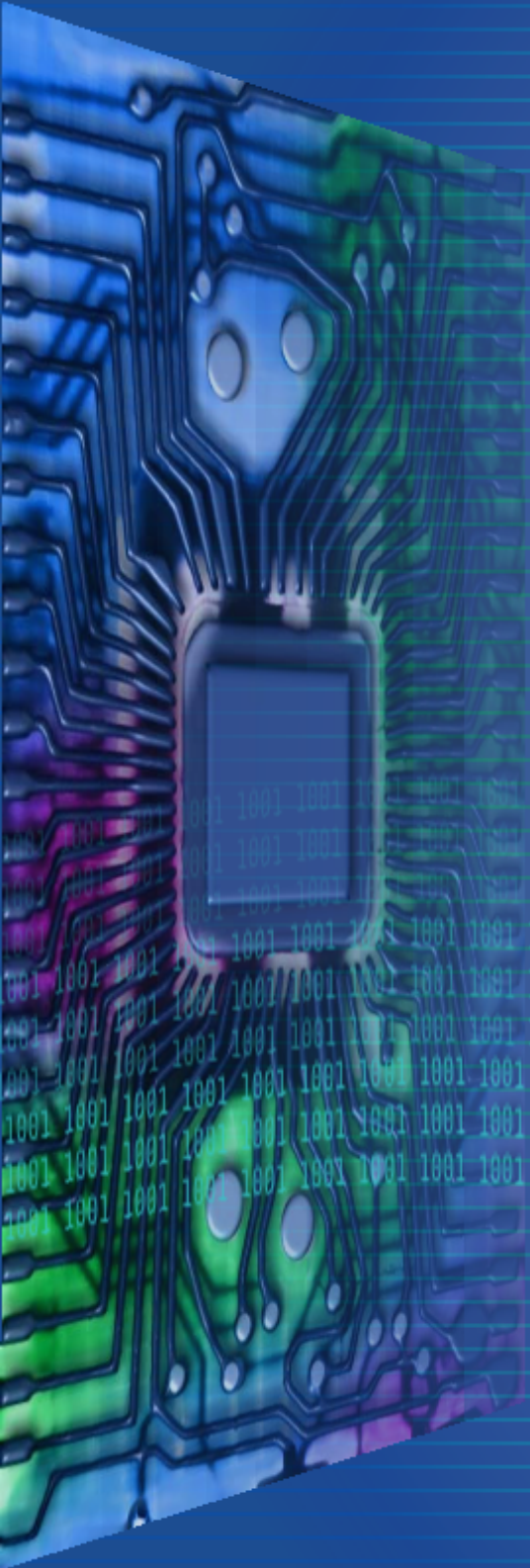
Presenter's bio

- French computer security engineer
- Main activities:
 - Penetration testing & security audits
 - Security trainings
(EC-Council CEH, ECSA/LPT, CHFI, CEI certified)
 - Security research
- Main interests:
 - Security of protocols (authentication, cryptography, information leakage, zero-knowledge proofs...)
 - Number theory (integer factorization, primality tests, elliptic curves)

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Intro

What is clock-skewing?

- Also known as “clock skew” or “timing skew”
- Drift compared to the actual exact time
- Negative or positive skew
- Why is there a drift?
 - Software implementation of clock
 - Material imperfections (e.g. quartz fabrication)
 - Differences in wire lengths
 - Differences in input capacitance
 - Intermediate components
 - ...

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Basis (1/2)

- The idea is to build a fingerprint from this drift
- Local or remote fingerprinting!
- Most important: correct time reference
- Then, target clock deviation measurements and clustering



Basis (2/2)

“The more imprecise is your clock,
the more precise will be your fingerprint!”



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The image features a vibrant, multi-colored circuit board on the left side, with a central square chip. The board is rendered in shades of blue, green, and purple. The background is a solid teal color with a faint, repeating pattern of binary code (0s and 1s) in a lighter shade. The text "How does it work?" is centered in a large, white, sans-serif font.

How does it work?

How does a computer handle time?

- In fact, it has 2 different clocks:
 - An hardware clock called “RTC” (Real time clock), made of quartz, battery powered
 - A software clock (“system clock”) handled by the OS kernel with a counter and interrupts (ticks)
- Under Linux & Windows:
 - Kernel synchronizes its software clock with RTC at boot time
 - RTC is almost never read after (even synchronizations are rare)



Measurement mechanisms

- First of all, we need the more precise local time for target drift measurement
- How to measure a clock?
 - Using a better clock!
- Better clocks:
 - Atomic clocks
 - GPS clocks (basically the same!)
 - Radio clocks (e.g. DCF77, TDF...)
- Typical atomic clock precision:
 - 1 s./3000 years
- Fortunately, atomic clocks can be queried using NTP protocol

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Correct time reference

- Windows (S)NTP client can only guarantee 1-2 second precision
- We should better use Linux NTP client for measurement (10-30 ms precision!)



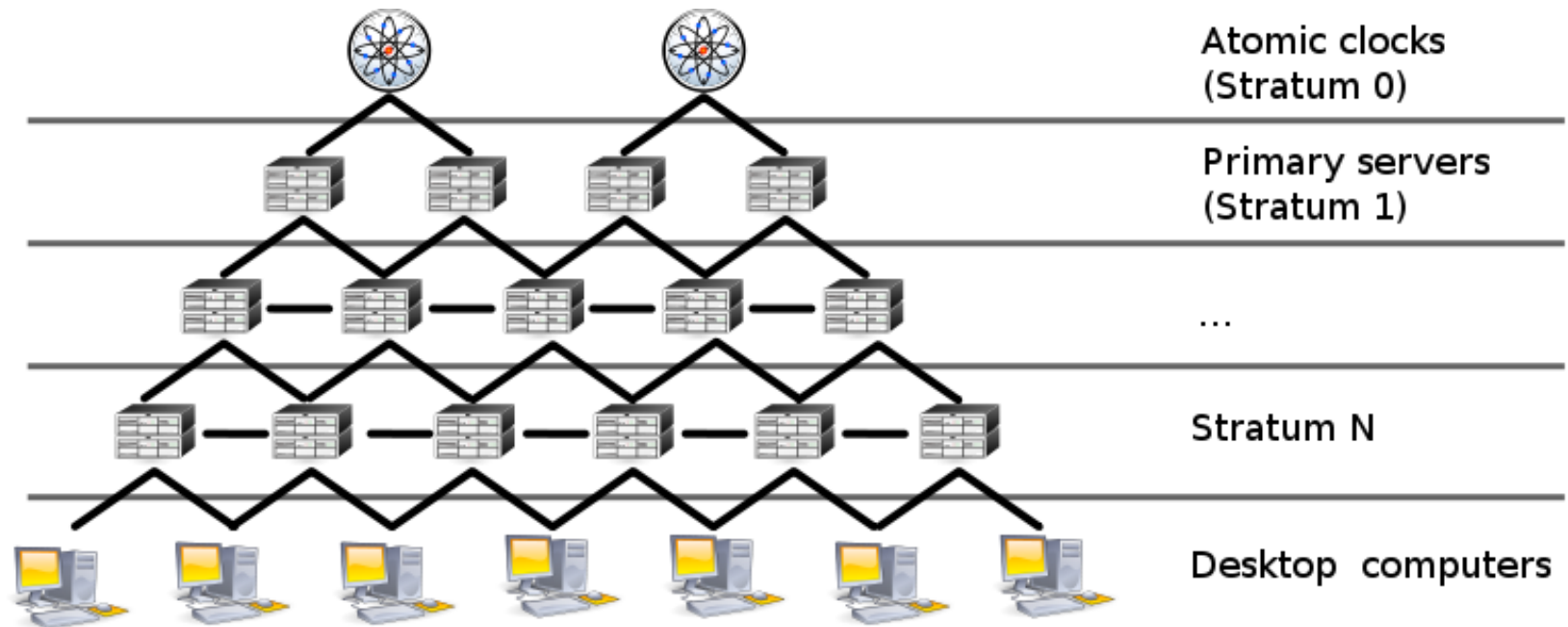
A few words about NTP (1/3)

- NTP = Network Time Protocol
- Protocol for synchronizing the clock of computer systems
- One of the oldest internet protocols (September 1985)
- Works with UDP, port 123
- NTP only adjusts the system clock rate so that system clock match exact time
- Precision (at best):
 - 10 ms over Internet
 - 200 μ s in LAN
- Common versions: NTP v3 (RFC 1305) & NTP v4



A few words about NTP (2/3)

- NTP uses a hierarchical, layered system of levels of clock sources:



A few words about NTP (3/3)



U.S. Naval Observatory in Colorado (Stratum 0 source)

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Active measurement of the target (1/2)

- One can remotely query the time of a target using “ICMP Timestamp Requests” packets (ICMP Type 13 Code 0)
- Target replies with “ICMP Timestamp Replies” (ICMP Type 14 Code 0)
- Number of milliseconds since midnight (GMT Time)
- Generated from system clock



Active measurement of the target (2/2)

```
### [ ICMP ] ###  
type= timestamp-reply  
code= 0  
chksum= 0x7012  
id= 0x0  
seq= 0x0  
ts_ori= 12:19:17.427  
ts_rx= 12:47:39.852  
ts_tx= 12:47:39.852
```

ICMP layer of an ICMP Timestamp Reply



Passive measurement of the target (1/2)

- Or semi-active!
- Using TCP timestamps
- Proportional to uptime
- Generated from tick counter only
- Seems more accurate than ICMP timestamps



Passive measurement of the target (2/2)

```
###[ TCP ]###
sport= telnet
dport= 56066
seq= 2240595391L
ack= 4265897507L
dataofs= 8L
reserved= 0L
flags= PA
window= 3032
chksum= 0x7017
urgptr= 0
options= [('NOP', None), ('NOP', None), ('Timestamp', (2775749850L, 3584624))]
```

TCP layer of a “timestamp-enabled” TCP packet

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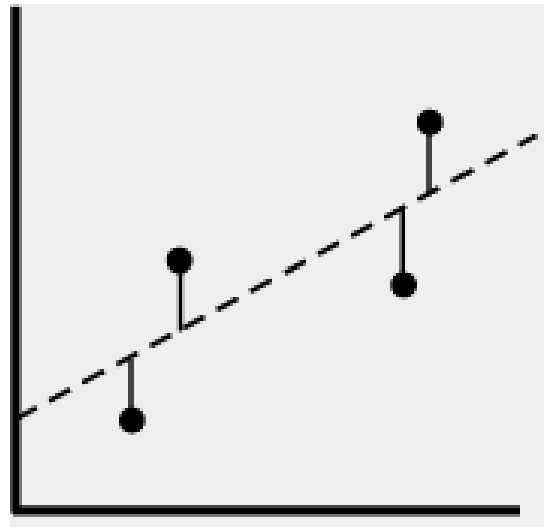
Precision & measurement resolution (1/3)

- We have to deal with 10ms of NTP precision and 30ms network latency
 - According to Tadayoshi Kohno's study, average drift:
 - is stable on a given computer (+/- 1-2 ppm)
 - varies up to +/- 50 ppm
- This gives 4-6 bits of information



Precision & measurement resolution (2/3)

- Least square fitting on the set of measurement points:
{(local host time, target time difference)}

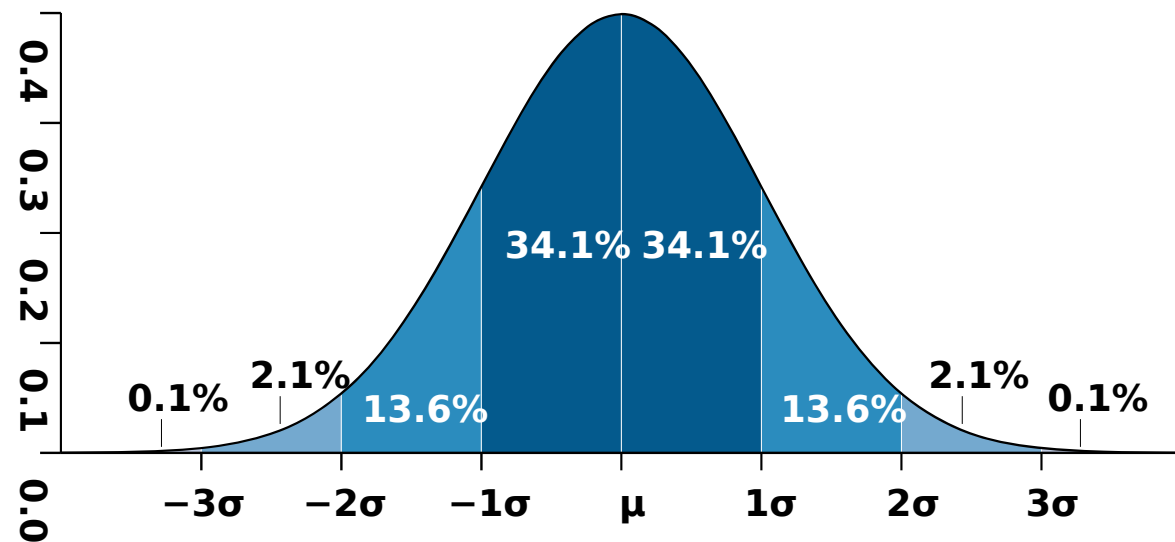


- Obviously, longer measurement = better precision



Precision & measurement resolution (3/3)

- Enhancement: we can add an additional measurement dimension to fingerprint target clock precision: standard deviation around average slope (if network latency is nearly constant)
 - adds 1-3 bits of information



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Distinguishing devices

- Using those 1 or 2-dimension measurements, we can easily define a distance measure between any 2 points
- Then, use any known multidimensional clustering algorithm:
 - Hierarchical algorithms
 - Partitional algorithms (e.g. k-means)
 - Density-based algorithms
- Ability to distinguish between about $2^{(6+3)}=512$ different computers on Internet
- Can be combined with other fingerprinting techniques for better efficiency (OS TCP/IP fingerprinting, IP IDs, banners...)

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Weaknesses

- Not so high resolution on Internet (need for longer measurement or additional characteristics)
- Sensitivity:
 - Temperature:
+/- 1 ppm in typical computer temperature
 - Altitude
 - High computer activity:
see known attacks on Tor anonymity network (ref. [1])





Applications

Identification of stolen devices

- Compute the fingerprint of your computer in case you lose it
- You are now able to find it remotely among hundreds of similar computers (a lot easier on a LAN)...
- ... even if IP address / MAC address / hard drive was changed! (OS type shouldn't have been changed...)



Detection of remote virtual machines

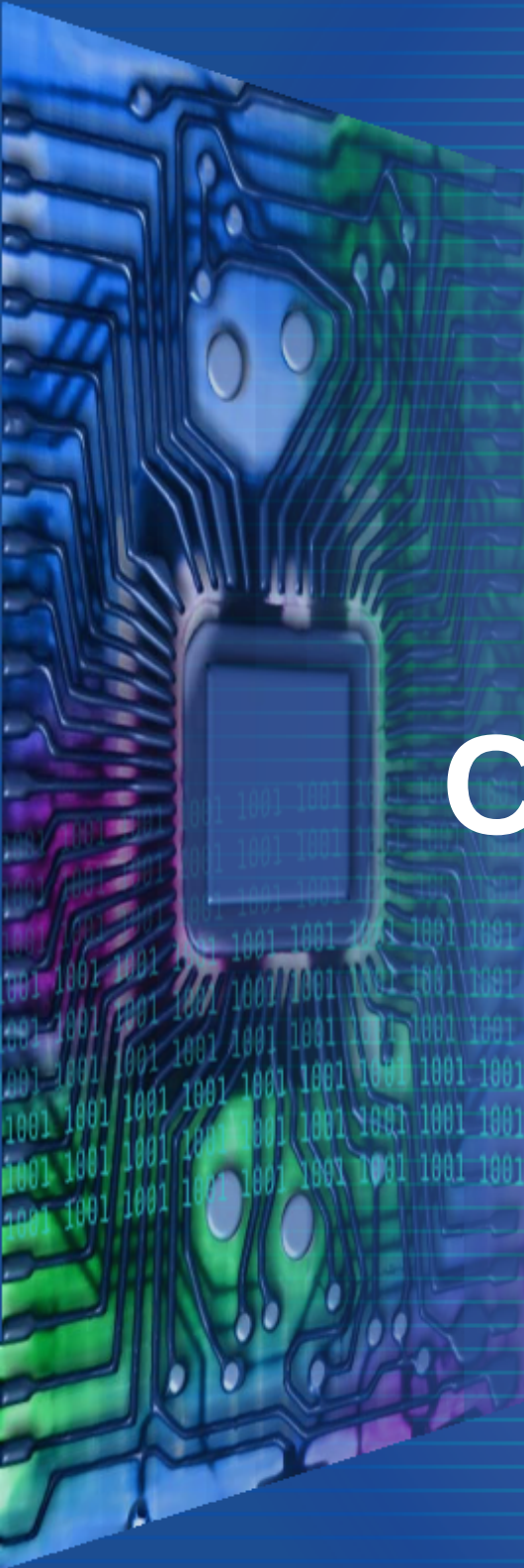
- If guest VMs are time-synchronized with host (option in most virtualization solutions), they will share a very similar fingerprint
- Otherwise, same guest OSes on the same host will have similar fingerprints



Computer forensics

- These kinds of fingerprints can be computed offline
- Fingerprints computed from a short PCAP network capture done on a well-synchronized computer
- Ability to fingerprint an attacker computer even if entire attack isn't completely recorded
- Compare attack fingerprint with suspected computer fingerprints





Countermeasures

Countermeasures

- Frequent NTP synchronizations
- Disable:
 - TCP timestamps
 - ICMP or ICMP timestamp requests/replies
 - Any service delivering time (or just the time functionality, not the service!): e.g. Apache “Date” HTTP header
- Regularly change:
 - Your temperature
 - Your altitude
 - Your computer activity
 - Your processor & motherboard!

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Tool & demo

Tool

- No tool seems to exist!
- Open source tool using Python & Scapy
- Very basic & naive tool for the moment
- “Quick and dirty” coded
- Tool will be published on Google Code just after the event
- Feel free to contribute & improve the tool!

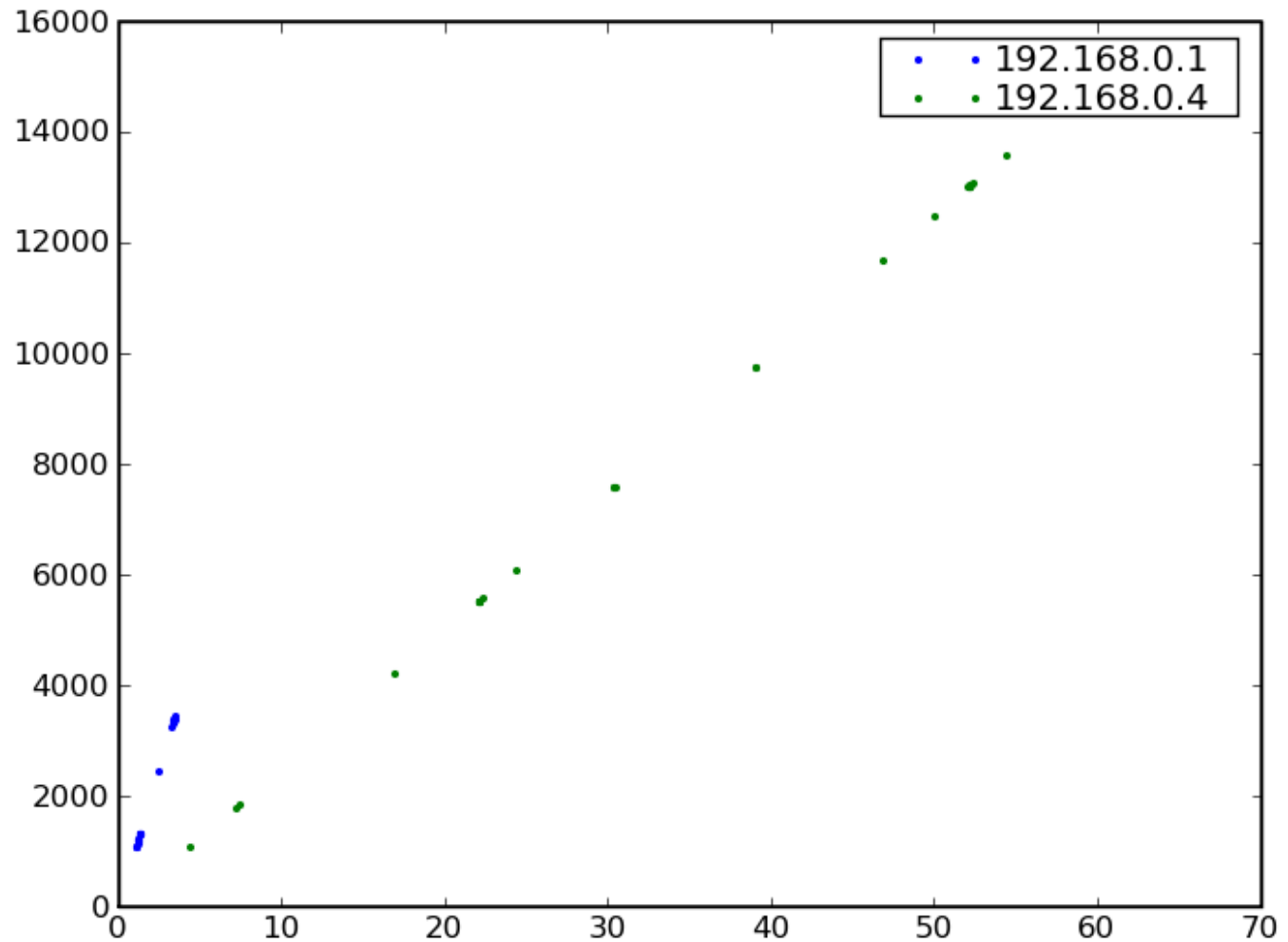


Live demo (1/2)

- Requirements:
 - Computers on a wired network (latency is too important on wireless networks):
either TCP or ICMP-enabled
 - Some NTP servers for suitable time synchronization
 - Python & Scapy installed



Live demo (2/2)



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Outro

References

- [1] Tadayoshi Kohno, Andre Broido, and K.C. Claffy, “Remote physical fingerprinting”, IEEE Transactions on Dependable and Secure Computing, 2(2):93-108, 2005.
- [2] Talk “Fingerprinting hosts through clock skew”, Steven Murdoch, EuroBSDCon, 2007
- [3] “NTP, une simple histoire de temps”, GNU/Linux Magazine France, Diamond Editions, April 2010

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Thanks!

Questions?